

# Technology Readiness Levels and Maturation Approaches for ISHM Technologies

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# Talk Outline

- > **Sources of difficulties**

Why is ISHM behind?

- > **Overview of regular TRLs**

Are our difficulties unique, or common to all technology efforts?

- > **Previous inadequacies: What did we do for software?**

What were the important differences? Are they similar to the ISHM case?

- > **ISHM specific changes to TRL**

Proposed new guidelines, as simple and non-invasive as possible

- > **Ways to handle the problems**

Near-term missions: Looking ahead five to ten years

- > **Example: F-18 Experience**

Applying some of these ideas in a pathfinding experiment



# Difficulties of ISHM

- > **ISHM technologies are inherently difficult to mature**
  - ◆ Treats exceptional behavior by definition
  - ◆ Poorly understood scenarios, few to no examples
  - ◆ VERY expensive to test thoroughly
  - ◆ Difficult to develop without retrofitting
- > **Key needed features of ISHM have never been attempted**
- > **State-of-art examples do not fully enclose ISHM**
  - ◆ 777, MER: Complicated system health management, but not truly integrated
    - 777: Driven by maintenance, flight schedules, ground operations
    - MER: Complex reasoning, even on-board behavior modification, but still largely a “learning” system
    - Cassini, other huge robotic spacecraft: Integrated, real-time response, close association with flight controls, but focused on reflexive actions rather than optimizing long-term reliability (“health *maintenance*”)
  - ◆ Missing features: Reasoning, system-level management, integration of different functions, flight- and safety-criticality



# Maturation Hurdles

## > Five particular hurdles complicate ISHM maturation

### ◆ Enumerability of states

- E.g. preparing for and testing multiple hypotheses

### ◆ The Problem of Nominal

- What does “Nominal” mean in a grey-scale universe?

### ◆ Can't Really Test ISHM

- Ability to test large components, let alone entire systems to failure, is rare

### ◆ Access to Data

- Chicken and egg problem, usually pushes us towards “retrofit”

### ◆ Algorithms vs. Models

- Certify a model? Or re-test the whole system just to reconfigure one element of a model? What to do?



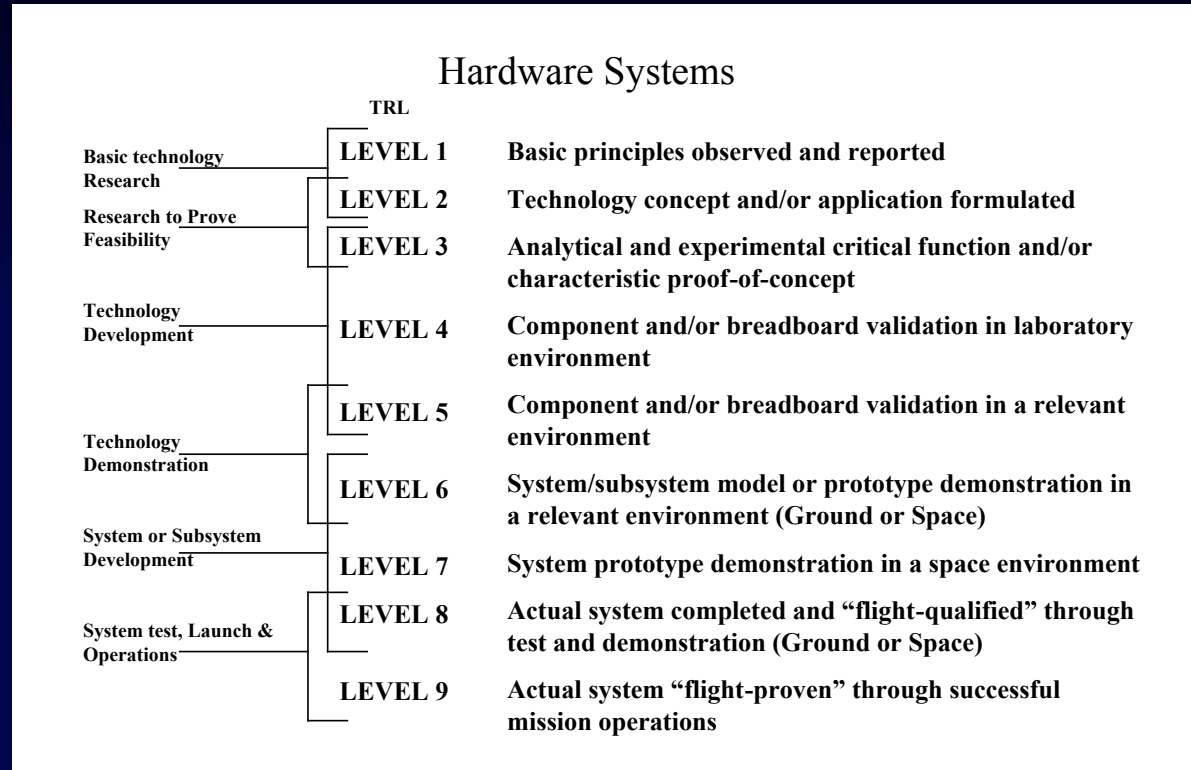


# Brief Recap of Ordinary TRL

> Note focus on hardware

> Key points:

- ◆ Performance Model
- ◆ Relevant Environment
  - “Stress testing”
- ◆ Meaning of Validation
  - Tightly coupled to performance model



> Other Issues

- ◆ Is “flown in space” equal to “validated in space?”
- ◆ When is a validation considered “full-scale?”



# TRL for ~~Software~~ Information Technologies

## > What did we need to change?

### ◆ What is *our* “relevant environment?”

- Most environmental issues have already been addressed by hardware providers
- IT environment is largely virtual, also much more emphasis on interfaces

### ◆ Execution environment? Development environment? Tools?

- Needed to introduce more of the IT development process
- Unlike hardware, development methods – debugging tools, compilers, etc. – have a complex impact on technology performance beyond feasibility

### ◆ Interfaces

- Many more interfaces in information environment

### ◆ Issue of running “on” hardware

- Is it possible to mature IT without maturing hardware in parallel?

## > What are the big difficulties facing software?

### ◆ Left to last minute

### ◆ Huge state-space

### ◆ Complex and badly understood environment



# Suggested TRL Changes for ISHM

- > **TRL 1 – Identified/invented and documented a useful ISHM technology with a qualitative estimate of expected benefit.**
  - ◆ Basic functional relationships of a potential application formulated *and shown to be compatible with reasonable ISHM architectures and testing requirements.*
- > **TRL 2 – Completed a breakdown of the ISHM technology into its underlying functions and components, and analyzed requirements and interactions with other systems.**
  - ◆ Defined and documented requirements for operation, interfaces, and relevant mission phases.
  - ◆ Preliminary design assessment confirmed compatibility *with the expected ISHM architecture.*
- > **TRL 3 – Major functions of ISHM technology prototyped to prove scientific feasibility. Successful preliminary tests of critical functions demonstrated and documented, leading to a preliminary performance estimate.**
  - ◆ Experiments with small representative data sets conducted.
  - ◆ *Execution environment and development tools required to conduct these tests, such as modeling tools, defined and documented.*



# Suggested TRL Changes for ISHM

- > **TRL 4 – Prototype completed on laboratory hardware and tested in a realistic environment simulation.**
  - ◆ Experiments conducted with full-scale problems or data sets in a laboratory environment and results of tests documented.
  - ◆ *Development ISHM infrastructure completed as needed for the prototype.*
  - ◆ A model of ISHM technology performance, adequate for prediction of performance in the intended application, must be documented as a result of these tests.
- > **TRL 5 – Prototype refined into a system and tested on simulated or flight-equivalent hardware.**
  - ◆ *Interaction environment, including interfaces to other systems, defined and included in the testing environment.*
  - ◆ *Rigorous stress testing completed in multiple realistic environments and documented.*
  - ◆ *Performance of the technology in the relevant environment must be documented and shown to be consistent with its performance model.*



# Suggested TRL Changes for ISHM

- > **TRL 6 – System ported from breadboard hardware testbeds to flight hardware and tested, along with all other needed components, in realistic simulated environment scenarios.**
  - ◆ ISHM technology tested in complete relevant execution environment.
  - ◆ *Engineering feasibility fully demonstrated.*

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- > **Early TRL: Need understanding of ISHM architecture**
  - ◆ Defines inputs, outputs, timing, and performance requirements
  - ◆ Integral part of the relevant environment.
- > **Relevant environment:**
  - ◆ Prototype or skeleton ISHM architecture, conforming to the envisioned final application
  - ◆ Sensors, computing hardware, message passing, etc. are all defined by that architecture
  - ◆ Stress-testing, for purposes of ISHM, means injection of faults – either simulated or real – that are considered limiting cases, either in terms of sensitivity, timing, or severity.



# Possible Maturation Solutions

## > Design for data capture

- ◆ Few programs currently realize the long-term value of system data
- ◆ Includes assembly and initial tests, and rarely requires additional sensors
- ◆ ISHM can also help find and correct errors during vehicle assembly and test

## > Prototype ISHM using mission or vehicle analogues

- ◆ Useful surrogate systems may exist
- ◆ Higher re-flight rates and greater fault injection and mission variation
- ◆ Confront “flight realism” as early as possible

## > Revisit flight-critical system requirements

- ◆ Not every fault can be anticipated, let alone invoked for testing purposes
- ◆ More realistic approaches:
  - Verify models through iterative “pathfinder” techniques
  - Certify resilience in case of “broken” ISHM
  - Separate highly critical, reflexive ISHM and test independently

## > Employ model-based engineering (MBE) approaches, autocoding, etc.

- ◆ Model-dependence emphasizes need for accuracy, completeness, and interoperability
- ◆ Autocoding, automatic model abstraction, and model checking simplifies certification
- ◆ Especially valuable as vehicle evolves

## > Construct and maintain a centralized “meta-environment” combining system, subsystem, and component models into a unified simulation

- ◆ Maintains data and domain knowledge
- ◆ Use to test and certify ISHM technologies
- ◆ Contains all “Relevant Environments” for different ISHM components



# Mapping Solutions to Problems

|   | Design for Data Capture                                     | Analogue Missions                                     | Negotiated Flight-Critical Requirements                                   | Autocoding and MBE   | Meta-Environmental Models  |
|---|---|---|---|--|--|
| <b>Difficulty of Full Scale Testing</b> | Gradual testing as system is assembled                      | Full-scale tests of equivalent system                 | More realistic testing requirements                                       | Organize unit testing  | Provide end-to-end simulation at various levels of detail                |
| <b>Poor Access to Data</b>              | Capture data and domain knowledge during assembly and test  | Access to extensive data of analogous system          |   |  | Playback and integration of captured data, synthesis with simulated data |
| <b>Imprecise Definition of Nominal</b>  | Mechanism to gather nominal data from system as it is built | Realistic flight testing, including nominal variation |   |  | Collect known variation within nominal                                   |
| <b>Algorithms vs. Models</b>            | Test models against actual data as system is constructed    | Test ability to generate and include model updates    | Permit certification of models without recertifying entire ISHM           | Automated generation and checking of models                          |  |
| <b>State Explosion</b>                  |   |   | Permit separation of ISHM to allow abstraction, independent certification | Allow optimal model testing using exhaustive or branch/bound methods | Provide and maintain a meaningful abstraction of state space             |





# Example Maturation Effort: F-18 Testbed

- > *Aircraft validation is one example of a “surrogate spacecraft” for NASA ISHM maturation*
  - ◆ REAL TEST DATA, and lots of it
    - > 40 hours of flight data in under three months
  - ◆ Simulating challenging situations for ISHM (“breaking stuff”) is easier
    - Can include exceptional situations, dummy broken hardware, even real broken hardware
    - Opportunistic scenarios
  - ◆ Aircraft are in some ways a *better* fit to human-rated flight than robotic spacecraft
    - Crew-rated vehicle
    - Complex environmental interaction
    - Similar time horizons (seconds, not hours)
  - ◆ Differences between space and aircraft *IT environment* can be closed easily
    - Flight computer, OS, databus, power spec all doable
    - Could include additional space hardware, e.g. sensors, true interfaces
  - ◆ Cheaper and faster
    - Needed to hit moving targets at NASA





# Maturation Experiment: IMS and BEAM

> **IMS: Inductive Monitoring System (ARC)**

> **BEAM: Beacon-based Exception Analysis for Multimissions (JPL)**

- ◆ Two separate mid-TRL ISHM technologies
- ◆ Monitoring and data interpretation (“Anomaly Detection”)
- ◆ Potential for real-time, on-board operation

> **Experiment Objectives:**

- ◆ Establish usefulness of F-18 testbed as a technology demonstrator
  - Characterize testbed for developers
  - Generate process of readiness review, integration on aircraft, flight, data recovery, analysis, improvement
  - Understand adaptability of testbed to new hardware
- ◆ Deliver hardware and software
- ◆ Access to data
  - How long to first flight? Reflight? Quality of data?
  - Other “real world” effects?

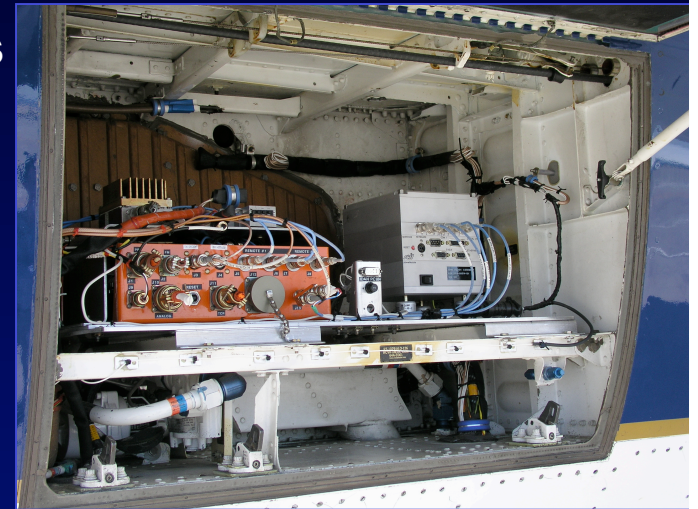


Benchmark F-18 process using BEAM and IMS as first customers

# F-18 Maturation: Where are we today?

## > F-18 proved to be an effective “icebreaker”

- ◆ Acquired needed hardware
- ◆ Achieved first data-taking flight in ~ 4 months
- ◆ Introduced realistic flight issues to developers
  - Power
  - Forces ready-for-flight reviews, etc.
  - Computing hardware constraints
  - Computing hardware idiosyncracies
  - Co-development of software and hardware
- ◆ Tremendous access to data
  - 23 individual flights, realistic operation
- ◆ Ability to modify, retest, reflly without lengthy delays
  - In practice, less than one week between update cycles
- ◆ Greater access to pilots, aircraft crew chief, etc.
- ◆ Flight and simulation both available
  - Also access to existing aircraft models (follow-on work)
- ◆ Tested nominal, in-flight faults, plus new discoveries...



# In Conclusion

- > **ISHM poses special challenges, but nothing intractable**
  - ◆ Know the common problems and plan to counter them early
- > **ISHM puts a new spin on the standard TRLs**
  - ◆ Similar to “hardware” vs. “software” concerns
  - ◆ Introduced some ISHM specific changes to TRL, keeping as simple and non-invasive as possible
  - ◆ Concepts of “Relevant Environment” and “Performance Model” take on more complex meaning
- > **Proposed a “covering set” of mitigation approaches**
  - ◆ Can solve the worst problems by considering requirements, knowledge capture, modeling, and broader applications of MBE
- > **Example: F-18 Experience**
  - ◆ Applied four of five mitigating techniques to mature technologies
  - ◆ So far, so good

